

Technical data sheet

Parameterisable damper actuator for adjusting air control dampers in ventilation and air-conditioning systems for building services installations

- For air dampers up to approx. 3.2 m²
- Torque 16 Nm
- Nominal voltage AC/DC 24 V
- Control: modulating DC 0 ... 10 V or variable
- Position feedback DC 2 ... 10 V or variable
- Running time 7 s or variable



Technical data

Electrical data				
Nominal voltage		AC 24 V, 50/60 Hz / DC 24 V		
Nominal voltage range		AC 19.2 28.8 V / DC 21.6 28.8 V		
Power consumption In operation		15 W @ nominal torgue		
At rest		2 W		
For wire sizing		26 VA (I max. 20 A @ 5 ms)		
Connection		Cable 1 m, 4 x 0.75 mm ²		
Functional data		Factory settings	Variable	Settings
Torque (nominal torque)		Min. 16 Nm @ nominal voltage	25%, 50%, 75% reduced	
Control Control signal Y		DC 0 10 V, input impedance 100 kΩ	Open-close, modulating (DC 0 32 V)	
Operating range		DC 2 10 V Starting point DC 0.5 30 V End point DC 2.5 32 V		
Position feedback (Measuring voltage)		DC 2 10 V, max. 0.5 mA	Starting pointDC 0.5 8 VEnd pointDC 2.5 10 V	
Position accuracy		±5%		
Direction of rotation		Reversible with switch 0 / 1		
Direction of motion at Y = 0 V		At switch position 0 🔨 resp. 1 🔿	Electronically reversible	
Manual override		Gearing latch disengaged with pushbutton, can be locked		
Angle of rotation		Max. 95°⊲, can be limited at both ends with adjustable mechanical end stops		
Angle of rotation limiting		min. 30°∢		
Running time		7 s / 90°∢ 7 35 s		
Automatic adjustment of operating range and measuring signal U to match the mechanical angle of rotation		Manual triggering of the adaption by pressing the «Adaption» button or with the PC-Tool voltage is switched on		
Override control		MAX (maximum position)= 100%MIN (minimum position)= 0%ZS (intermediate position, only AC)= 50%	MAX = (MIN + 30°⊲) 100% MIN = 0% (MAX – 30°⊲) ZS = MIN MAX	
Sound power level 52 dB (A) With a 7 s = 52 dB (A)				
Position indication		Mechanical, pluggable		
Negative torque	⚠	≤50% from nominal torque (Caution: can only be used with restrictions. Please contact your Belimo representative.)		
Safety				
Protection class		III Safety extra-low voltage UL Class 2 Supply		
Degree of protection		IP54 in any mounting position NEMA 2, UL Enclosure Type 2		
EMC		CE according to 2004/108/EC		
Certification		Certified to IEC/EN 60730-1 and IEC/EN 6073 cULus according to UL 60730-1A and UL 6073 and CAN/CSA E60730-1:02	-	
Mode of operation		Type 1		

Parameterisable damper actuator, AC/DC 24 V, 16 Nm.



SMQ24A-MF	Parameterisable damper actuator, AC/DC 24 V, 16 Nm, running time 7 s			
Technical data	(Continued)			
Safety				
Rated impulse voltage	0.8 kV			
Control pollution degree	3			
Ambient temperature	-30 +40°C (no restrictions)			
Å	+40 +50 °C (Caution: can only be used			
—	with restrictions. Please contact your Belimo			
	representative.)			
Non-operating temperature	-40 +80 °C			
Ambient humidity	95% r.H., non-condensating			
Maintenance	Maintenance-free			
Dimensions / Weight				
Dimensions	See «Dimensions» on page 6			
Weight	Approx. 970 g			
Safety notes	 The actuator is not allowed to be used outside the specified field of application, especially in aircraft or in any other airborne means of transport. 			
	 It may only be installed by suitably trained personnel. Any legal regulations or regulations issued by authorities must be observed during assembly. 			
	 The device may only be opened at the manufacturer's site. It does not contain any parts that can be replaced or repaired by the user. 			
	 The cable must not be removed from the device. 			
	 Adaptation is necessary when the system is commissioned and after each adjustment of the angle (press the adaptation push-button) 			
	 When calculating the required torque, the specifications supplied by the damper manufacturers (cross section, design, installation site), and the air flow conditions must be observed. 			
	 The device contains electrical and electronic components and is not allowed to be disposed of as household refuse. All locally valid regulations and requirements must be observed. 			
Product features				
Mode of operation	The actuator is controlled with a standard modulating signal of DC 0 10 V and moves to the position defined by the control signal. The measuring voltage U serves for the electrical display of the damper position 0 100% and as slave control signal for other actuators.			
Parameterisable actuators	The factory settings cover the most common applications. Input and output signals and other parameters can be altered with the BELIMO Service Tool, MFT-P.			
Simple direct mounting	ng Simple direct mounting on the damper spindle with a universal spindle clamp, supplied with an anti-rotation strap to prevent the actuator from rotating.			
Manual override	Manual override with push-button possible (the gear is disengaged for as long as the button is pressed or remains locked).			
Adjustable angle of rotation	 Adjustable angle of rotation with mechanical end stops. A minimum permissible angle of rotation of 30° must be allowed for. 			
High functional reliability	y The actuator is overload-proof, requires no limit switches and automatically stops when the end stop is reached.			
Home position	The first time the supply voltage is switched on, i.e. during initial startup, the actuator carries out an adaptation. After pressing the «gear disengagement» pushbutton, the actuator moves to the home position at the end stop.			
	Pos. Direction of rotation Home position			
	\searrow Y = 0 \checkmark Left stop			
	$(\bigcirc)_{1} \qquad (\bigcirc)_{1} \qquad (\bigcirc)_$			
	The actuator then moves into the position defined by the control signal.			

During adaptation, the upper and lower spindle end stop is recorded and deposited in the Adaption and synchronisation actuator. Detection of the mechanical end stops enables a gentle approach to the end positions and thus protects the actuator mechanism. During synchronisation, the actuator moves to the home position for angle referencing. This ensures correct position regulation.

Parameterisable damper actuator, AC/DC 24 V, 16 Nm, running time 7 s



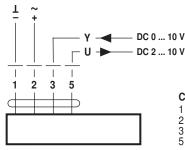
Accessories

	Description	Data sheet
Electrical accessories	Auxiliary switch SA	T2 - SA
	Feedback potentiometer P.A.	T2 - PA
	Adapter Z-SPA	
	Ordering of this adapter is compulsory if an auxiliary switch or a feedback potentiometer is required and the clamp is simultaneously mounted on the	
	rear of the actuator (e.g. with short-spindle mounting).	
	PC-Tool MFT-P from version 3.3	T2 - MFT-P
	Positioner SG24	T2 - SG24
	Range controller SBG24	T2 - SBG24
	Room temperature controller CR24	S4 - CR24
	Digital position indication ZAD24	T2 - ZAD24
echanical accessories	Various accessories (clamps, shaft extensions etc.)	T2 - Z-GMA

Electrical installation

Wiring diagram

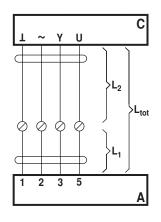
- Note
- Connect via safety isolation transformer.
- Parallel connection of other actuators possible.
- Note performance data for supply.





- 1 = black 2 = red3 = white
- 3 = wnite5 = orange

Cable lengths



A = Actuator

C = Control unit

 L_1 = Belimo connecting cable, 1 m (4 x 0.75 mm²)

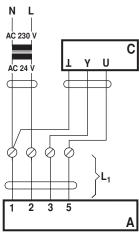
 L_2 = Customer cable

Ltot = Maximum cable length

Cross section L ₂	Max. cable length $L_{tot} = L_1 + L_2$				Example for DC
L / ~	AC	DC			
0.75 mm ²	≤30 m	≤5 m	1 m (L ₁) + 4 m (L ₂)		
1.00 mm ²	≤40 m	≤8 m	1 m (L ₁) + 7 m (L ₂)		
1.50 mm ²	≤70 m	≤12 m	1 m (L ₁) + 11 m (L ₂)		
2.50 mm ²	≤100 m	≤20 m	1 m (L ₁) + 19 m (L ₂)		

Note

When several actuators are connected in parallel, the maximum cable length must be divided by the number of actuators.



$\begin{array}{rcl} \textbf{C} &= & \text{Control unit} \\ \textbf{L}_1 &= & \text{Belimo connecting cable, 1 m (4 x 0.75 mm^2)} \end{array}$

= Actuator

Α

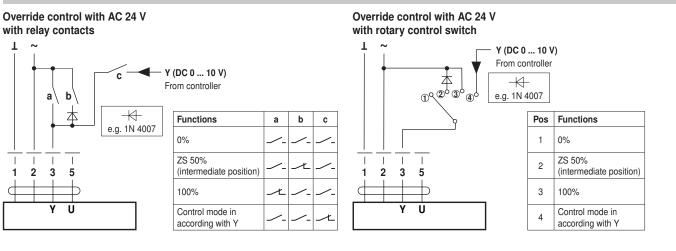
Note

There are no special restrictions on installation if the supply and data cable are routed separately.

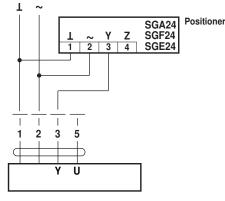
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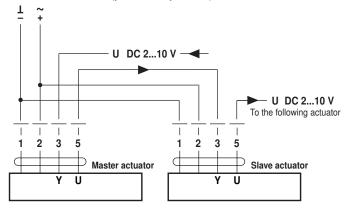
Functions with basic values



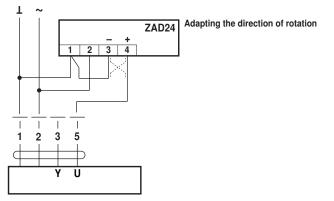




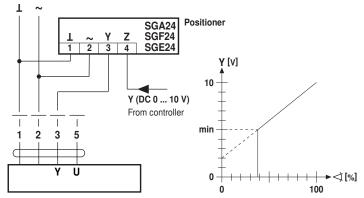
Master/Slave control (position-dependent)



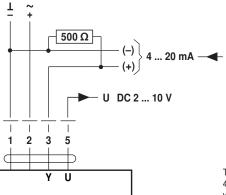
Position indication



Minimum limit

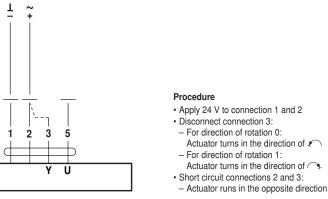






The 500 Ω resistor converts the 4 ... 20 mA current signal into a voltage signal DC 2 ... 10 V





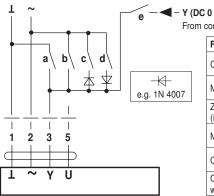
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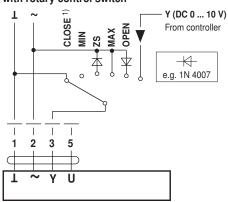
Functions for actuators with specific parameters

Override control and limiting with AC 24 V with relay contacts



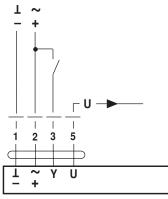
0 10 V) controller					
Functions	а	b	с	d	е
CLOSE 1)	_L				<u></u> _
MIN	<u></u>	<u></u>	<u></u>	<u></u>	<u></u>
ZS (intermediate position)	∕-	/-	Ŀ	∕-	<u></u> _
MAX	-/-	Ł	-/-	-/-	-⁄-
OPEN			-/-	-⁄Ľ	<u></u>
Control mode in acc. with Y	∕-	∕-	∕-	<u></u>	Ŀ

Override control and limiting with AC 24 V with rotary control switch



¹⁾ Caution! This function is only guaranteed if the start point of the operating range is defined as min. 0.6 V.

Open-close control



Operating controls and indicators



(1) Direction of rotation switch

Switching over: Direction of rotation changes

- 2 Push-button and green LED display
- Off: No voltage supply or fault On: In operation

Switches on angle of rotation adaptation followed by standard operation Press button:

(3) Push-button and yellow LED display

Off:	Standard operation
On:	Adaptation or synchronising process active
Press button:	No function

(4) Gear disengagement switch

Gear disengaged, motor stops, manual override possible Press button: Release button: Gear engaged, synchronisation starts, followed by standard operation

5 Service plug

b)

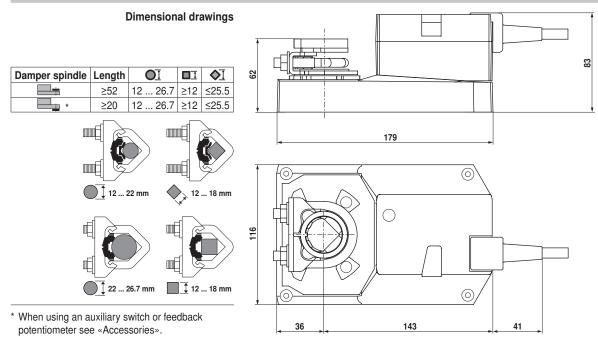
For connecting parameterising and service tools

Check voltage supply connection

- 2 Off and 3 On a)
 - Check the supply connections. (2) Blinking and (3) Blinking Possibly \perp and $\widetilde{+}$ are swapped over.



Dimensions [mm]

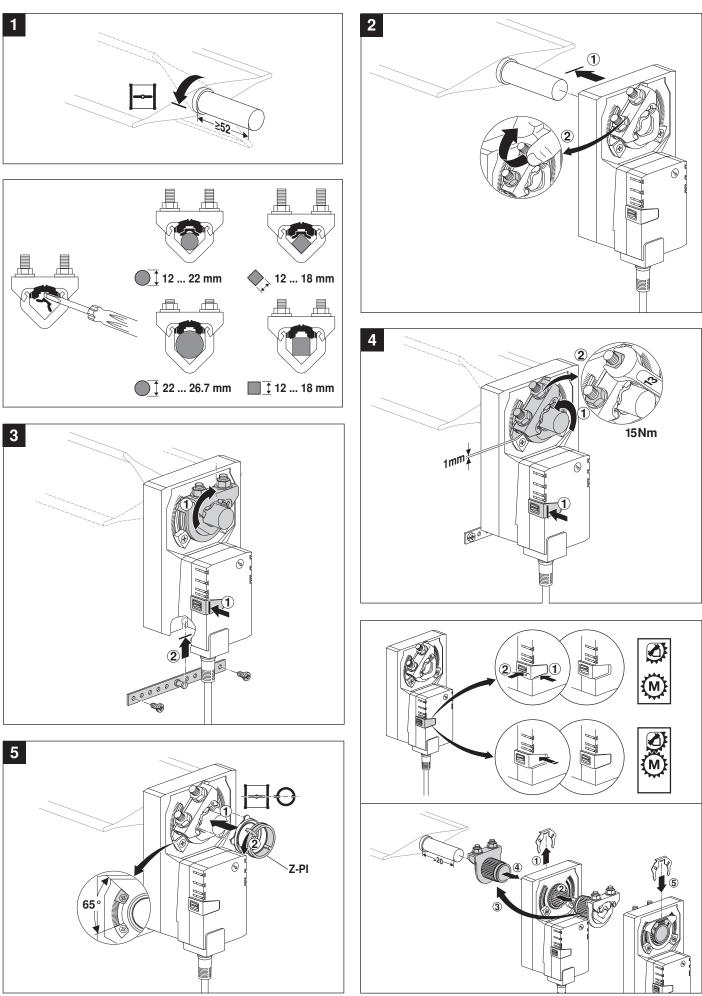


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SMQ24A.. / SMD24R



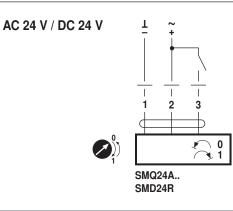
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AC 24 V / DC 24 V

